

Systems of linear equations over a bounded chain

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§ 1. Introduction

The equivalence, reduction and minimization are classical problems for the theory of abstract automata. They are completely studied for deterministic, non-deterministic and stochastic automata (8). These problems are still open for fuzzy automata because there does not exist a polynomial time algorithm for solving systems of linear equations over a bounded chain.

Let $\mathbf{L}=(L, \vee, \wedge, 0, 1)$ be a bounded chain (5) with underlying linearly ordered set L , the greatest element 1 and the smallest element 0. We shall write \mathbf{L} instead of $\mathbf{L}=(L, \vee, \wedge, 0, 1)$.

For a given set D we denote by $|D|$ its cardinality.

Let \mathbf{L} be given. Let $I \neq \emptyset, J \neq \emptyset$ be sets of indices. We write $B \in L^{I \times J}$ for the matrix $B=(b_{ij})$ where $b_{ij}=b(i, j)$ is the (i, j) -th entry of a map $b: I \times J \rightarrow L$.

Let J be finite set and $A=(a_{ij}) \in L^{I \times J}, B=(b_{jk}) \in L^{J \times K}$ be given. The matrix $C=A \cdot B=(c_{ik}) \in L^{I \times K}$ is called a *product* of A and B if

$$c_{ik} = \bigvee_{p=1}^{|J|} (a_{ip} \wedge b_{pk}) \text{ for each } i \in I, k \in K.$$

Obviously $c_{ik} \in \{a_{ip}: p \in J\} \cup \{b_{pk}: p \in J\}$.

Let $A=(X, Q, Y, M)$ be a fuzzy automaton (7, 9) with input alphabet X , state set Q , output alphabet Y and set of the step-behaviour matrices

$$M = \{M(x/y): x \in X, y \in Y\}.$$

Each $M(x/y)=(m(x/y)_{qq'}) \in L^{|Q| \times |Q|}$ and $m(x/y)_{qq'}$ is the grade of membership of a transition to state q' under input x assuming the output is y and the start state is q . If X, Q, Y are finite sets then A is finite fuzzy automaton.

For any set D we write D^* for the free monoid on D with the empty word $e \in D^*$ as the identity element. For $(u, v) \in X^* \times Y^*$ we write (u/v) if the number of the letters in u is equal to that of the letters in v .

Let $A=(X, Q, Y, M)$ be a finite automaton. The expression

$$M(u/v) = M(x_1/y_1) \dots M(x_k/y_k), \quad u = x_1 \dots x_k \in X^*, \quad v = y_1 \dots y_k \in Y^*$$

defines the operation of A for the pair of words (u/v) . Let

$$M(u/v) = (m(u/v)_{qq'}).$$

For the given automaton A let us consider its behaviour matrix

$$B^* = (b(u/v)_q), \quad q \in Q, \quad (u/v) \in X^* \times Y^*,$$

where $b(u/v)_q = \bigvee_{q' \in Q} m(u/v)_{qq'}$ is the grade of membership of the output v upon the input u when the start state is q . The matrix B^* is semi-infinite with $|Q|$ rows.

It is well-known (7, 9) that there exists a finite submatrix B of B^* with linearly independent columns. For the problems of equivalence, reduction and minimization of fuzzy automata the main question is how to compute B from B^* . That means for any column in B^* we have to answer whether it is a \bigvee - \bigwedge -linear combination of the previous columns in B^* . If we can solve systems of linear equations over a bounded chain then we can compute B from B^* .

In this paper the attention is concentrated on computing a solution of the system of linear equations over \mathbf{L} . The main result is (see Algorithm 3 and the Theorem corresponding to it) that there exists a polynomial time algorithm for solving a system of linear equations over a bounded chain. An extension of this result for some semirings is given in (6).

We would like to remark that the classical methods (5) for solving systems of linear equations over a field are not useful here because \mathbf{L} is not a field. Since the conjugate matrix for a given matrix in \mathbf{L} does not exist in general, the ideas of (1) can not be applied. As our problem is essentially different from the extremal linear programming (10) these results can not be implemented.

Further we shall use without explicit explanation the concept of computational complexity as described in (3) and the properties of chains according to (5).

§ 2. Linear equations over \mathbf{L}

In order to determine the general solution of the system we consider first a linear equation in \mathbf{L} .

By $A \cdot X = b$ we denote the following linear equation

$$(a_1 \wedge x_1) \vee \dots \vee (a_n \wedge x_n) = b \quad (1)$$

with coefficients $A = (a_j) \in L^{(1) \times J}$, unknowns $X = (x_j) \in L^{J \times (1)}$ and a constant $b \in L$. Here $\{1\}$ stands for the singleton set and we assume $|J| = n \in \mathbf{N}$.

The matrix $X^0 = (x_j^0) \in L^{J \times (1)}$ is a *point solution* of (1) if and only if $A \cdot X^0 = b$ holds. If there exists X^0 with $A \cdot X^0 = b$ then the equation (1) is called *solvable*, otherwise it is *unsolvable*. An n -tuple (X_1, \dots, X_n) of intervals $X_i \subseteq L$ is called an *interval solution* of (1) if every n -tuple (x_1, \dots, x_n) with $x_i \in X_i$ is a point solution of (1) and (X_1, \dots, X_n) is maximal with respect to this property.

Let the equation (1) be given and

$$S = \{j \in J: a_j < b\}, \quad E = \{j \in J: a_j = b\}, \quad G = \{j \in J: a_j > b\}$$

Proposition 1. The equation (1) is solvable if and only if $E \cup G \neq \emptyset$ and the interval solutions are the n -tuples (X_1, \dots, X_n) where for each $j \in J$ either

each $i \in I$

$$\exists j \in J: (a'_{ij} \cong x_j = b'_i) \Leftrightarrow$$

$$\exists j \in J: (a'_{ij} \cong b'_i \wedge x_j = b'_i) \vee (a'_{ij} = b'_i \wedge x_j \cong b'_i) \Leftrightarrow$$

$$\exists j \in J: (a^*_{ij} = 1 \wedge x_j = b'_i) \vee (a^*_{ij} = b'_i \wedge x_j \cong b'_i),$$

i.e. for each $i \in I$ there exists a $j \in J$ such that $a^*_{ij} \wedge x_j = b'_i$ and hence $A^* \cdot X = B'$.

Let $\underline{B} = \{b_1, \dots, b_m\}$ be the set of the distinct elements in the matrix B of the system (2), resp. (2'). Having in mind the expression (4), it is clear that the elements a^*_{ij} of A^* and b'_i of B' belong to the set $\underline{B} \cup \{0, 1\}$.

Proposition 5. Let $X = (X_j)$ be an interval solution of the system $A^* \cdot X = B'$, where the components X_j , $j \in J$, are determined by (3). Each component X_j is among the following intervals: L , $[0, b_{p1}]$, $[b_{p2}, b_{p3}]$, $[b_{p4}, 1]$, where $b_{p1}, b_{p2}, b_{p3}, b_{p4} \in \underline{B}$. The proof follows from Proposition 1 and the expression (3).

Corollary 1. Each interval solution of (2) has all its components among the following intervals: L , $[0, b_{p1}]$, $[b_{p2}, b_{p3}]$, $[b_{p4}, 1]$, where $b_{p1}, b_{p2}, b_{p3}, b_{p4} \in \underline{B}$.

Let B_m^n be the set of all n -fold variations with repetitions on the elements of the set \underline{B} .

Corollary 2. The system (2) is solvable if and only if there exists an $X^0 \in B_m^n$ such that $A \cdot X^0 = B$ holds.

Proof. If there exists an $X^0 \in B_m^n$ with $A \cdot X^0 = B$ then the system (2) is solvable. Conversely, if the system (2) is solvable, then each component X_j of an interval solution has the interval form determined by Corollary 1. Hence we can choose each component x_j^0 of a point solution of (2) to be equal to an element of \underline{B} , i.e. $X^0 \in B_m^n$.

Having in mind Corollary 2 we propose the following algorithm for computing a point solution of the system (2), or for establishing its solvability.

Algorithm 2

Step 1. Find the set \underline{B} .

Step 2. Compute the set B_m^n .

Step 3. For each $X^0 \in B_m^n$ check whether it is a point solution of the system (2).

Step 4. List all point solutions determined in Step 3.

Step 5. If there exists no $X^0 \in B_m^n$ with $A \cdot X^0 = B$ then the system is unsolvable. Otherwise it is solvable and a set of point solutions is given in step 4.

Proposition 6. The time complexity function of Algorithm 2 is exponential in the number of n variables.

Proof. We can check whether $X^0 \in B_m^n$ is a solution of (2) in a polynomial time, but in a search problem manner. The set B_m^n is finite and $|B_m^n| = |\underline{B}|^n \cong m^n$. Hence the Algorithm 2 is finite with exponential in the number of n variables time complexity function.

§ 4. A polynomial time algorithm

We propose a polynomial time algorithm for computing a point solution of the system (2) if it is solvable or for listing the numbers of the contradictory equations if the system is unsolvable.

In order to simplify the problem we introduce a symbol-matrix \underline{A} with symbol-coefficients obtained from those of A^* if for each a_{ij}^* we put the corresponding type letter S , E or G (without index):

$$a_{ij} = \begin{cases} S & \text{if } a_{ij}^* = 0, \\ E & \text{if } a_{ij}^* = b'_i, \\ G & \text{if } a_{ij}^* = 1. \end{cases} \quad (5)$$

The set of the solutions of the system (2) remains unchanged after this reduction step (5).

Let the system (2) be given and $X=(X_j)$ denote an interval solution of (2). Let the system (2') and the matrix \underline{A} be obtained. We assume $j \in J$ to be fixed in \underline{A} . In the following we denote by r the smallest number of the row with E -type coefficient in its j^{th} column and by k the greatest number of the row with G -type coefficient in its j^{th} column in \underline{A} .

In order to find a point solution of (2) we are interested in finding a point $x_j \in X_j$ with $a_{ij} \wedge x_j \leq b_i$ for each $i \in I$. Especially we mark the i^{th} equation in a marker vector IND if $a_{ij} \wedge x_j = b_i$ holds.

Having in mind the above notions we obtain the following

Proposition 7. Let the system $A \cdot X = B$ be given.

i) if the j^{th} column in \underline{A} contains a G -type coefficient then $x_j = b'_k$ implies $a_{ij} \wedge x_j = b'_i$ for $i=k$ and for each $i > k$ with $a_{ij} = b'_i$;

ii) if the j^{th} column in \underline{A} does not contain any G -type coefficient but it contains an E -type coefficient then $x_j = b'_r$ implies $a_{ij} \wedge x_j = b'_i$ for $i=r$ and for each $i > r$ with $a_{ij} = b'_i$;

iii) if the j^{th} column in \underline{A} does not contain neither G -type nor E -type coefficients then $a_{ij} \wedge x_j < b'_i$ for each $x_j \in L$.

Proof. i) if $x_j = b'_k$ and $i=k$ then $a_{ij} \wedge x_j = a'_{kj} \wedge b'_k = b'_k$ since $a'_{kj} > b'_k$; if $x_j = b'_k$, $i > k$ and $a_{ij} = b'_i$ then $a_{ij} = b'_i \leq b'_k$ according to the order in (2') implies $a_{ij} \wedge x_j = b'_i \wedge b'_k = b'_i$;

ii) if $x_j = b'_r$ and $i=r$ then $a_{ij} \wedge x_j = a'_{rj} \wedge b'_r = b'_r \wedge b'_r = b'_r$; if $x_j = b'_r$, $i > r$ and $a_{ij} = b'_i$ then $a_{ij} = b'_i \leq b'_r$ according to the order in (2') implies $a_{ij} \wedge x_j = b'_i \wedge b'_r = b'_i$;

iii) if the j^{th} column in \underline{A} contains only S -type coefficients then $a_{ij} \wedge x_j \leq a'_{ij} < b'_i$ for each $i \in I$ and arbitrary $x_j \in L$.

On this base we propose the following algorithm:

Algorithm 3

Step 1. Enter the matrix $(A:B)$.

Step 2. Form the matrix \underline{A} .

Step 3. Erase the marker vector IND .

Step 4. $j=0$.

Step 5. $j=j+1$.

Step 6. If $j > n$ go to 10.

Step 7. If the j^{th} column in \underline{A} does not contain any G -type coefficient then go to 8. Otherwise $x_j = b'_k$. Put a mark in IND for $i = k$ and for each $i > k$ with $a'_{ij} = b'_i$. Put a mark in IND for each $i < k$ if $a'_{ij} \cong b'_i = b'_k$. Go to Step 5.

Step 8. If the j^{th} column does not contain any E -type coefficient then go to step 9. Otherwise $x_j = b'_r$, put marks in IND for $i = r$ and for each $i > r$ with $a'_{ij} = b'_i$. Go to Step 5.

Step 9. $x_j = 1$. Go to Step 5.

Step 10. If there exists at least one unmarked row in IND then the system is unsolvable and the unmarked equations are in contradiction with the marked ones. The marked equations form a compatible system. If all rows in IND are marked then the system is compatible and the components of the point solution $X = (x_i)$ are determined in Steps 7, 8, 9.

Theorem. The following problems are algorithmically decidable in polynomial time for the system (2):

- i) whether the system is solvable or not;
- ii) computing a point solution if the system is solvable;
- iii) obtaining the numbers of the contradictory equations if the system is unsolvable.

The proof follows from Algorithm 3.

The program realisation of Algorithm 3 is available at the Center of Applied Mathematics in the Higher Institute for Mechanical and Electrical Engineering.

We shall consider two examples as a simple illustration of Algorithm 3.

Example 1. Solve the system

$$(0,3 \wedge x_1) \vee (0,5 \wedge x_2) \vee (0,4 \wedge x_3) \vee (0,7 \wedge x_4) = 0,2$$

$$(0,8 \wedge x_1) \vee (0,2 \wedge x_2) \vee (0,7 \wedge x_3) \vee (0,5 \wedge x_4) = 0,5$$

$$(0,2 \wedge x_1) \vee (0,7 \wedge x_2) \vee (0,5 \wedge x_3) \vee (0,3 \wedge x_4) = 0,3$$

The (\vee) -system is

$$(0,8 \wedge x_1) \vee (0,2 \wedge x_2) \vee (0,7 \wedge x_3) \vee (0,5 \wedge x_4) = 0,5$$

$$(0,2 \wedge x_1) \vee (0,7 \wedge x_2) \vee (0,5 \wedge x_3) \vee (0,3 \wedge x_4) = 0,3$$

$$(0,3 \wedge x_1) \vee (0,5 \wedge x_2) \vee (0,4 \wedge x_3) \vee (0,7 \wedge x_4) = 0,2$$

The matrix $(A:B')$ and the marker vector IND are

$$(A: B') = \begin{pmatrix} G & S & G & E & 0,5 \\ S & G & G & E & 0,3 \\ G & G & G & G & 0,2 \end{pmatrix} \quad IND = \begin{pmatrix} 0 \\ 0 \\ * \end{pmatrix}$$

The system is unsolvable. The contradictory equations have 0 in IND .

Example 2. Compute a point solution of the system

$$(0,2 \wedge x_1) \vee 0,5 \wedge x_2 \vee (0,7 \wedge x_3) = 0,4$$

$$(0,8 \wedge x_1) \vee (0,2 \wedge x_2) \vee (0,1 \wedge x_3) = 0,2$$

The matrix $(\underline{A}: B')$ and the marker vector IND are

$$(\underline{A}: B') = \begin{pmatrix} S & G & G: 0,4 \\ G & E & S: 0,2 \end{pmatrix} \quad IND = \begin{pmatrix} * \\ * \end{pmatrix}$$

The column vector $X=(0,2 \ 0,4 \ 0,4)'$ is a point solution of this system.

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Abstract. A polynomial time algorithm for computing a point solution of a system of linear equations over a bounded chain is given.

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