

Note on the Work Function Algorithm

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Abstract

We prove that the work function algorithm is $(n - 1)$ -competitive for the k -server problem, where n is the number of points in the metric space. This gives improved upper bounds when $k + 3 \leq n \leq 2k - 1$; in particular, it shows that the work function algorithm is optimal for $k = n - 1$. Recently this result was proved independently by Koutsoupias in [K].

1 Introduction

We give a short introduction to the deterministic k -server problem ([ST], [MMS]). There is a metric space \mathcal{M} with a distance function $d(\cdot, \cdot)$ on it. Let us denote $|\mathcal{M}|$ by n . There are k ($1 < k < n$) mobile servers initially residing on the pointset I , no two on the same point. Repeatedly requests are generated by an off-line adversary, and we have to satisfy them in an on-line fashion. Satisfying a request is putting a server on the requested point of the metric space. When moving a server, a cost occurs which is the distance of the previous and the present position of the server which is moved. While the adversary has the advantage that it satisfies the request sequence at the end thus it can satisfy them optimally paying the least, an on-line algorithm pays after every request. In competitiveness analysis we compare the on-line cost with the optimal (off-line) cost, we are looking for an algorithm with the best competitive ratio. In [MMS] it is proved that no on-line algorithm can have competitive ratio less than k . They also gave optimal on-line algorithm for two special cases: when $k = 2$ and when $k = n - 1$. They conjectured that in every case there is an optimal, k -competitive on-line algorithm. There are other cases with optimal on-line algorithms: when the metric space is tree-like ([CL]), when every distance is the same (paging problem, [ST]), or for the weighted cache problem ([CKPV]). So far the best general on-line algorithm is given by Koutsoupias and Papadimitriou ([KP1]). They proved that the work function algorithm is $(2k - 1)$ -competitive. In another paper ([KP2]) they also showed that the work function algorithm is k -competitive if $k + 2 = n$. In this paper we give a proof that their

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algorithm is $(n - 1)$ -competitive as well, hence for $k + 3 \leq n \leq 2k - 1$ this gives the best known upper bounds, and for $k = n - 1$ it proves that the work function algorithm is optimal. In [K] Koutsoupias proved this result by considering the so called weak adversaries for the k -server problem. Our paper gives a simple alternative proof.

The outline of this note is as follows: in the next chapter we present a brief description of the work function algorithm, and state some relevant properties of it, without proofs. Then in the third chapter we prove our result.

2 Work Function Algorithm

Let \mathcal{M} , I and the request sequence ρ is given. Then the work function w_ρ maps configurations to nonnegative real numbers: $w_\rho(X)$ is the optimal cost of servicing ρ starting at I and ending at X . For a work function w_ρ the resulting work function after the request r is $w_{\rho r}$. The following proves to be very useful:

Fact 2.1 For all X $w_{\rho r}(X) \geq w_\rho(X)$.

Let us now define the algorithm itself.

Definition 2.2 (Work Function Algorithm) Let ρ be a request sequence and A be the configuration of the servers after satisfying ρ . The work function algorithm services the new request at r by moving one of the servers to the configuration $B = A - a + r$ (i.e., the server moves from a to r), where $w_{\rho r}(B) + d(a, r)$ is minimal.

The so called extended cost of a move, $\max_X \{w_{\rho r}(X) - w_\rho(X)\}$ in some way encapsulates the optimal and the on-line costs.

Fact 2.3 If the sum of the extended costs is bounded above by $c + 1$ times the optimal cost plus a constant, then the work function algorithm is c -competitive.

The notion of minimizer configurations is also an important one.

Definition 2.4 A configuration A is called a minimizer with respect to the point a with respect to w_ρ if

$$w_\rho(A) - \sum_{x \in A} d(a, x) = \min_X \{w_\rho(X) - \sum_{x \in X} d(a, x)\}. \quad (1)$$

We finish describing the relevant definitions and facts by the following lemma, the *Duality Lemma*.

Lemma 2.5 (Duality Lemma) Let w_ρ be a work function, and let $w_{\rho r}$ be the resulting work function after request r . Then any minimizer A of r with respect to w_ρ is also a minimizer of r with respect to $w_{\rho r}$, and the extended cost of servicing the request r is $w_{\rho r}(A) - w_\rho(A)$.

3 Proof of the $(n - 1)$ -competitivity

Let ρ be the request sequence, and let the next request be r . Denote A_x the minimizer configuration of x with respect to w_ρ , and B_x the minimizer configuration of x with respect to $w_{\rho r}$. Let us define a potential function P_ρ :

$$P_\rho = \sum_x \left[w_\rho(A_x) - \sum_{a \in A_x} d(x, a) \right]. \tag{2}$$

Analogously, we can define $P_{\rho r}$. Denoting the empty request sequence by \emptyset one may observe, that P_\emptyset , the initial potential function is a constant. In the sequel by $\text{opt}(\rho)$ we will denote the optimal cost of satisfaction of the request sequence ρ .

Lemma 3.1 (1) $P_{\rho r} - P_\rho \geq$ extended cost of the move from ρ to ρr and
 (2) $P_\rho - n \cdot \text{opt}(\rho) \leq$ constant.

Proof. For proving (1) observe that A_r is a minimizer of r with respect to w_ρ and $w_{\rho r}$. Thus, $w_{\rho r}(A_r) - \sum_{a \in A_r} d(r, a)$ is also a minimal expression, and $w_{\rho r}(A_r) - w_\rho(A_r) =$ extended cost. Let now v be another point of \mathcal{M} , then $w_\rho(A_v) - \sum_{a \in A_v} d(v, a) \leq w_\rho(B_v) - \sum_{b \in B_v} d(v, b) \leq w_{\rho r}(B_v) - \sum_{b \in B_v} d(v, b)$. This proves (1). For proving the second part of the statement, observe that P_ρ is the sum of optimal costs plus a constant. \square

Theorem 3.2 *The work function algorithm is $(n - 1)$ -competitive.*

Proof. Summing up the potential function values over all requests we can see from Lemma 3.1 that this sum is at least the sum of the extended costs plus a constant. By Fact 2.3 we can conclude the statement of the theorem. \square

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