On DR Tree Automata, Unary Algebras and Syntactic Path Monoids

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\textit{To the memory of Zoltán Ésik}

Abstract

We consider deterministic root-to-frontier (DR) tree recognizers and the tree languages recognized by them from an algebraic point of view. We make use of a correspondence between DR algebras and unary algebras shown by Z. Ésik (1986). We also study a question raised by F. Gécseg (2007) that concerns the definability of families of DR-recognizable tree languages by syntactic path monoids. We show how the families of DR-recognizable tree languages path-definable by a variety of finite monoids (or semigroups) can be derived from varieties of string languages. In particular, the three path-definable families of Gécseg and B. Imreh (2002, 2004) are obtained this way.

Keywords: deterministic root-to-frontier tree automaton, tree language, unary algebra, syntactic path monoid, variety of finite monoids, variety of languages

1 Introduction

The tree languages recognized by deterministic root-to-frontier (top-down) tree recognizers form a proper subfamily $DRec$ of the family $Rec$ of all recognizable tree languages. The members of $DRec$, the DR-recognizable tree languages, are characterized by the fact that they are completely determined by the labeled paths appearing in their trees (cf. [11, 15, 16, 20]). Any path from the root of a tree to one of its leaves is represented as a word over the so-called path alphabet. Each symbol of this alphabet indicates both the label of a node of a tree and the direction taken at that node. If we group together the paths leading to a leaf labeled with a given symbol $x$ of the leaf alphabet $X$, then all the paths appearing in the trees of a given tree language $T$ form a family $(T_x)_{x \in X}$ of languages over the path alphabet, and if $T$ is DR-recognizable, it is completely determined by these languages $T_x$. This implies that the DR-recognizable tree languages resemble string languages more than general recognizable tree languages do. In particular, while few known

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families of recognizable tree languages can be characterized by syntactic monoids or semigroups, Gécseg and Imreh [7, 8] could characterize three subfamilies of $DRec$, those of DR nilpotent, DR monotone and DR definite tree languages, in terms of the syntactic path monoids or semigroups introduced in [12]. We shall show that there exist many more such examples: any $\ast$- or $+$-variety of string languages, as defined by Eilenberg [2], yields a subfamily of $DRec$ that can be characterized by syntactic path monoids or semigroups.

If we regard the path alphabet as a unary ranked alphabet, then the path set of a tree language $T$ becomes a unary tree language $\delta(T)$ that carries the same information as the family $\langle T_x \rangle_{x \in X}$. A DR recognizer may be seen as a finite DR algebra equipped with an initial state and a final state assignment. In [3] Zoltán Ésik associated with each DR algebra a unary algebra over the path alphabet, and noted that using this association one may apply ideas of standard general algebra to DR algebras. We complete the bijection between the two types of algebras by the converse transformation from unary algebras to DR algebras. The usefulness of this bijection derives from the fact that it preserves subalgebras, homomorphisms, congruences and direct products. In particular, we may refer to varieties of finite unary algebras when considering varieties of finite DR algebras. By extending this correspondence to tree recognizers, we study the connections between DR-recognizable tree languages and their unary path languages.

We shall recall or introduce all the special concepts used here. The basic universal algebra needed can be found in the first two chapters of [1], for example. For tree automata and tree languages, the reader may consult [11] and for the theory of varieties of (string) languages the books [2] and [17].

This paper is dedicated to the memory of Zoltán Ésik whom I learned know already in the 1970s. He has made many important contributions in several areas of theoretical computer science, and all his work is characterized by mathematical elegance and precision. It is a pleasure to acknowledge the inspiration I got from one of his, probably less well known, papers.

2 Preliminaries

For any integer $n > 0$, let $[n] = \{1, \ldots, n\}$. Let $A$ be any set. For any $i \in [n]$, let $\pi_i : A^n \to A, (a_1, \ldots, a_n) \mapsto a_i$ be the $i$th projection map. The power-set of $A$ is denoted by $\wp(A)$. If $\varphi : A \to B$ is a mapping, the image $\varphi(a)$ of an element $a \in A$ may be denoted also by $a\varphi$. Especially homomorphisms will be written this way as right operators. For any equivalence $\theta \in \text{Eq}(A)$ on $A$, we write $a\theta$ for the $\theta$-class of an element $a \in A$, and $A/\theta := \{a\theta \mid a \in A\}$ is the quotient set. For any alphabet $X$, the set of (finite) words over $X$ is denoted by $X^*$ and the empty word by $\varepsilon$.

Let $\Sigma$ be a ranked alphabet, i.e., a finite set of operation symbols, which does not contain nullary symbols. For each $m \geq 1$, $\Sigma_m$ denotes the set of $m$-ary symbols in $\Sigma$. The rank type of $\Sigma$ is the set $r(\Sigma) := \{m \mid \Sigma_m \neq \emptyset\}$. In what follows, $\Sigma$ is always a ranked alphabet of rank type $R$ and $X$ is an ordinary finite non-empty alphabet, called a leaf alphabet, disjoint from $\Sigma$. The set $T_\Sigma(X)$ of $\Sigma.X$-trees is the
least set such that $X \subseteq T_\Sigma(X)$, and $f(t_1, \ldots, t_m) \in T_\Sigma(X)$, for all $m \in R$, $f \in \Sigma_m$ and $t_1, \ldots, t_m \in T_\Sigma(X)$. A $\Sigma$-$X$-tree language is any subset of $T_\Sigma(X)$. Often we speak about trees and tree languages without specifying the alphabets.

A $\Sigma$-algebra $A$ consists of a nonempty set $A$ and a $\Sigma$-indexed family of operations on $A$ such that if $f \in \Sigma_m$ ($m \in R$), then $f^A : A^m \to A$ is an $m$-ary operation. We write $A = (A, \Sigma)$, and call $A$ finite if $A$ is a finite set. Subalgebras, homomorphisms, congruences etc. are defined as usual. For any class $K$ of $\Sigma$-algebras, let $S(K)$ consist of all algebras isomorphic to a subalgebra of a member of $K$, $H(K)$ be the class of all images of members of $K$, and $P_f(K)$ be the class of algebras isomorphic to a finite direct product of members of $K$. A class $K$ of finite $\Sigma$-algebras is a variety of finite $\Sigma$-algebras (a $\Sigma$-VFA for short) if $S(K)$, $P_f(K)$, $P_1(K) \subseteq K$. The $\Sigma$-VFA generated by a class $K$ of finite $\Sigma$-algebras is denoted by $V_f(K)$.

The $\Sigma$-$X$-term algebra $\mathcal{T}_\Sigma(X) = (T_\Sigma(X), \Sigma)$ is defined by setting, for all $m \in R$, $f \in \Sigma_m$ and $t_1, \ldots, t_m \in T_\Sigma(X)$, $f^T_\Sigma(X)(t_1, \ldots, t_m) = f(t_1, \ldots, t_m)$.

A $\Sigma$-$X$-recognizer $A = (A, \alpha, F)$ consists of a finite $\Sigma$-algebra $A = (A, \Sigma)$, an initial assignment $\alpha : X \to A$, and a set $F \subseteq A$ of final states. The $\Sigma$-$X$-tree language recognized by $A$ is the set $T(A) := \{ t \in T_\Sigma(X) \mid \alpha t \alpha \in F \}$ where $\alpha t \alpha : T_\Sigma(X) \to A$ is the homomorphic extension of $\alpha$. A $\Sigma$-$X$-tree language is called recognizable, or regular, if it is recognized by a $\Sigma$-$X$-recognizer. Let $Rec(\Sigma, X)$ denote the set of all recognizable $\Sigma$-$X$-tree languages.

If $\Sigma = \Sigma_1$, we call $\Sigma$ a unary alphabet and $\Sigma$-algebras are unary algebras. A unary alphabet $\Sigma$ may also be treated as an ordinary alphabet and we write $\Sigma$-terms as expressions $\xi u$, where $\xi$ is a variable and $u \in \Sigma^*$. The term functions induced by such terms $\xi u$ in a $\Sigma$-algebra $C = (C, \Sigma)$ are mappings $u^C : C \to C$, $c \mapsto cu^C$, defined by $ce^C = c$ and $cu^C = g^C(cv^C)$ for $u = vg$ ($v \in \Sigma^*$, $g \in \Sigma$).

On the other hand, we may view an ordinary (finite) alphabet $Z$ as a unary ranked alphabet and define $Z$-automata as unary algebras $A = (A, Z)$ in which each letter $z \in Z$ induces a unary operation $z^A : A \to A$, $a \mapsto az^A$. For any word $w = z_1 \ldots z_k \in \Sigma^*$ ($k \geq 0, z_1, \ldots, z_k \in Z$), the operation $w^A : A \to A$ is the composition of $z_1^A$, $\ldots, z_k^A$. A $Z$-recognizer is now a system $A = (A, a_0, F)$, where $A = (A, Z)$ is a finite $Z$-algebra, $a_0 \in A$ is the initial state, and $F \subseteq A$ is the set of final states. The language recognized by $A$ is the set $L(A) := \{ w \in \Sigma^* \mid a_0w^A \in F \}$. A language $L \subseteq \Sigma^*$ is regular if it is recognized by a $Z$-recognizer.

Often we will say that a string or tree language is recognized by an algebra $A$ if it is recognized by a recognizer of an appropriate kind based on $A$.

### 3 DR algebras and unary algebras

In what follows, the frequently recurring phrase deterministic root-to-frontier is abbreviated to DR. The following basic algebraic notions for DR algebras were defined by Virágh [20], but most of them are obtained from those defined for DR tree recognizers in [10]. To simplify the notation, we extend mappings and equivalence relations to $m$-tuples: if $\vec{a} = (a_1, \ldots, a_m) \in A^m$, then for any map $\varphi : A \to B$, let $\vec{a}\varphi := (a_1\varphi, \ldots, a_m\varphi)$, and for any $\theta \in Eq(A)$, let $\vec{a}\theta := (a_1\theta, \ldots, a_m\theta)$. 
A (finite) DR $\Sigma$-algebra consists of a nonempty (finite) set $A$ and a $\Sigma$-indexed family of root-to-frontier operations $f_A : A \rightarrow A^n$ ($f \in \Sigma$), where the arity $m$ is that of $f(\in \Sigma_m)$. Again we write simply $A = (A, \Sigma)$.

Let $A = (A, \Sigma)$ and $B = (B, \Sigma)$ be any DR $\Sigma$-algebras. Then $A$ is a subalgebra of $B$ if $A \subseteq B$ and $f_A(a) = f_B(a)$ for all $f \in \Sigma$ and $a \in A$. A mapping $\varphi : A \rightarrow B$ is a homomorphism from $A$ to $B$, and we write $\varphi : A \rightarrow B$, if $f_A(a)\varphi = f_B(a\varphi)$ for all $f \in \Sigma$ and $a \in A$. If $\varphi$ is also bijective, it is an isomorphism, and we write $A \cong B$ if $A$ and $B$ are isomorphic. The direct product of $A$ and $B$ is the DR $\Sigma$-algebra $A \times B = (A \times B, \Sigma)$ such that for all $m \in R$, $f \in \Sigma_m$ and $(a, b) \in A \times B$, if $f_A(a) = (a_1, \ldots, a_m)$ and $f_B(b) = (b_1, \ldots, b_m)$, then $f_{A \times B}((a, b)) = ((a_1, b_1), \ldots, (a_m, b_m))$. The general finite direct product $A_1 \times \cdots \times A_n$ ($n \geq 0$) is defined the same way.

A congruence on $A$ is an equivalence $\theta$ on $A$ such that for any $a, a' \in A$ and $f \in \Sigma$, if $a\theta a'$, then $f_A(a\theta) = f_A(a'\theta)$. Let $\text{Con}(A)$ denote the set of all congruences on $A$. For any $\theta \in \text{Con}(A)$, the quotient DR algebra $A/\theta = (A/\theta, \Sigma)$ is defined by $f_{A/\theta}(a\theta) := f_A(a\theta)$ for all $a \in A$ and $f \in \Sigma$.

All the usual facts about subalgebras, homomorphisms, congruences, etc. hold for DR algebras, too. For example, the kernel of any homomorphism $\varphi : A \rightarrow B$ is a congruence on $A$, and $A/\ker \varphi \cong B$ if $\varphi$ is surjective.

The tree languages recognized by deterministic root-to-frontier recognizers are characterized by the labeled paths appearing in their trees. The paths are described using the path alphabet $\bar{\Sigma} := \bigcup_{m \in R} \Sigma_m \times [m]$. A pair $(f, i) \in \bar{\Sigma}$ is written simply as $f_i$. We regard $\bar{\Sigma}$ either as a unary ranked alphabet or as an ordinary alphabet.

Following ´Esik [3] we associate with any DR $\Sigma$-algebra $A = (A, \Sigma)$ a unary algebra $A^u = (A, \bar{\Sigma})$ such that $f_A^u(a) = f_A(a)i$ for all $a \in A$, $m \in R$, $f \in \Sigma_m$ and $i \in [m]$. Let us also introduce a converse transformation: for any $\bar{\Sigma}$-algebra $C = (C, \bar{\Sigma})$, let $C^u = (C, \Sigma)$ be the DR $\Sigma$-algebra with $f_C^u(c) = (f_C^u(c), \ldots, f_C^u(c))$ for all $c \in C$, $m \in R$ and $f \in \Sigma_m$. Since $A^{vd} = A$ for any DR $\Sigma$-algebra $A$ and $C^{ud} = C$ for any $\bar{\Sigma}$-algebra $C$, there is a natural bijective correspondence between DR $\Sigma$-algebras and $\bar{\Sigma}$-algebras.

**Lemma 3.1.** Let $A = (A, \Sigma)$ and $B = (B, \Sigma)$ be any DR $\Sigma$-algebras.

(a) $A$ is a subalgebra of $B$ if and only if $A^u$ is a subalgebra of $B^u$.

(b) A mapping $\varphi : A \rightarrow B$ is a homomorphism from $A$ to $B$ if and only if it is a homomorphism from $A^u$ to $B^u$.

(c) $(A \times B)^u = A^u \times B^u$.

(d) $\text{Con}(A) = \text{Con}(A^u)$.

(e) $(A/\theta)^u = A^u/\theta$ for any $\theta \in \text{Con}(A)$.

**Proof.** All five statements follow directly from the appropriate definitions, and (c) was noted already in [3]. Let us verify (e) as an example.

Firstly, $(A/\theta)^u$ and $A^u/\theta$ are $\bar{\Sigma}$-algebras with the same set $A/\theta$ of elements. Moreover, for any $a \in A$, $m \in R$, $f \in \Sigma_m$ and $i \in [m]$,

$$f_i^{(A/\theta)^u}(a\theta) = f_{A/\theta}(a\theta)i = f_A(a\theta)i = f_A(a)i\theta = f_A^u(a)\theta = f_A^u/\theta(a\theta),$$
so also their operations are the same.

4 DR tree recognizers and unary recognizers

Let us now extend the correspondence between DR algebras and unary algebras to recognizers. A DR \(\Sigma\)-recognizer \(A = (A, \alpha, \nu)\) consists of a finite DR \(\Sigma\)-algebra \(A = (A, \Sigma)\), an initial state \(\alpha_0 \in A\), and a final state assignment \(\alpha : X \rightarrow \nu(A)\). To accept or reject an input tree \(t \in T_\Sigma(X)\), \(A\) starts at the root of \(t\) in state \(\alpha_0\), and if it has reached a node \(\nu\) of \(t\) labeled with \(f \in \Sigma_m\) in state \(a\) and \(f_a(a) = (a_1, \ldots, a_m)\), then it continues its working at the \(i^{th}\) immediate successor node of \(\nu\) in state \(a_i\) \((i \in [m])\). The tree is accepted if \(A\) reaches each leaf in a state \(a \in A\) matching the label \(x \in X\) of that leaf, i.e., \(a \in \alpha(x)\). For a formal definition, we extend \(\alpha\) to a mapping \(\tilde{\alpha} : T_\Sigma(X) \rightarrow \nu(A)\) by setting \(\tilde{\alpha}(x) = \alpha(x)\) for each \(x \in X\), and \(\tilde{\alpha}(t) = \{a \in A \mid f_a(a) \in \tilde{\alpha}(t_1) \times \ldots \times \tilde{\alpha}(t_m)\}\) for \(t = f(t_1, \ldots, t_m)\). Then \(T(A) = \{t \in T_\Sigma(X) \mid a_0 \in \tilde{\alpha}(t)\}\) is the tree language recognized by \(A\), and the \(\Sigma\)-tree language \(T(A)\) is said to be DR-recognizable. Let \(DRec(\Sigma, X)\) be the set of DR-recognizable \(\Sigma\)-tree languages. Two DR \(\Sigma\)-recognizers \(A\) and \(B\) are equivalent if \(T(A) = T(B)\).

The set \(\delta(t) \subseteq T_\Sigma(X)\) of paths in a \(\Sigma\)-tree \(t\) is defined by \(\delta(x) = \{x\}\) for \(x \in X\), and \(\delta(t) = f_1 \delta(t_1) \cup \ldots \cup f_m \delta(t_m)\) for \(t = f(t_1, \ldots, t_m)\). Thus \(\delta(t)\) is a set of unary trees in Polish form. The path language of a \(\Sigma\)-tree language \(T\) is the set \(\delta(T) := \bigcup\{\delta(t) \mid t \in T\}\). The path closure \(\Delta(T) := \delta^{-1}(\delta(T))\) of \(T \subseteq T_\Sigma(X)\) consists of all \(\Sigma\)-trees \(t\) such that \(\delta(t) \subseteq \delta(T)\), and \(T\) is path closed if \(T = \Delta(T)\).

Quite generally, for any \(U \subseteq T_\Sigma(X)\), the set \(\delta^{-1}(U) := \{t \in T_\Sigma(X) \mid \delta(t) \subseteq U\}\) is path-closed. As shown in [16], a regular tree language is DR-recognizable if and only if it is path closed. For properties of the operators \(\delta\) and \(\Delta\), cf. [15, 20].

Remark 4.1. Let \(\Sigma\) be unary. Then \(\hat{\Sigma} = \{f_i \mid f_i \in \Sigma\}\) and we may use \(\Sigma\) itself as the path alphabet. Furthermore, we may regard any DR \(\Sigma\)-algebra \(A = (A, \Sigma)\) also as a \(\Sigma\)-algebra by identifying any 1-tuple \((a)\) with the element \(a \in A\), but as a DR \(\Sigma\)-recognizer and as a \(\Sigma\)-recognizer \(A\) reads the input trees in opposite directions. Nevertheless, it is clear that \(DRec(\hat{\Sigma}, X) = Rec(\Sigma, X)\) for every \(X\).

Let us now regard \(\hat{\Sigma}\) as a usual alphabet. For each \(x \in X\), the set of \(x\)-paths in a \(\Sigma\)-tree \(t\) is \(g_x(t) := \{u \in \hat{\Sigma}^* \mid ux \in \delta(t)\}\). For any \(T \subseteq T_\Sigma(X)\) and \(x \in X\), let \(T_x\) denote the set \(\bigcup\{g_x(t) \mid t \in T\}\) of \(x\)-paths appearing in \(T\). Obviously, \(\delta(T)\) can be recovered from the family \(\langle T_x \rangle_{x \in X}\).

Next we recall a few notions from [10, 11]. Let \(A = (A, \alpha_0, \alpha)\) be a DR \(\Sigma\)-recognizer and \(A = (A, \Sigma)\). For any \(a \in A\), let \(A_a := (A, a, \alpha)\). A state \(a\) is a 0-state if \(T(A_a) = \emptyset\), and it is reachable if \(a_0 \Rightarrow^*_A a\) for the reflexive transitive closure \(\Rightarrow^*_A\) of the relation \(\Rightarrow A \subseteq A \times A\), where for any \(a, b \in A\), \(a \Rightarrow A b\) if and only if \(b = f_a(a)\). The recognizable \(\Sigma\)-tree \(t\) is normalized, if for all \(m \in R, f \in \Sigma_m\) and \(i \in [m]\), the recognizer \(A\) implies \(a = b\) \((a, b \in A)\), connected if all of its states are reachable, and it is minimal...
if it is connected and reduced. In [10] it was shown that any DR $\Sigma X$-recognizer can be converted into an equivalent normalized minimal DR $\Sigma X$-recognizer, and this is also minimal with respect to the number of states and unique up to isomorphism (the isomorphism of DR $\Sigma X$-recognizers is defined in the natural way, cf. [10]).

Let us associate with any DR $\Sigma X$-recognizer $A = (A, a_0, \alpha)$ the DR $\hat{\Sigma} X$-recognizer $A^u = (A^u, a_0, \alpha)$, and with any DR $\hat{\Sigma} X$-recognizer $C = (C, c_0, \gamma)$ the DR $\Sigma X$-recognizer $C^d = (C^d, c_0, \gamma)$. Obviously, $A^{ud} = A$ and $C^{du} = C$.

**Proposition 4.1.** $T(A) = \delta^{-1}(T(A^u))$ for any DR $\Sigma X$-recognizer $A$.

**Proof.** Let $A = (A, a_0, \alpha)$ with $A = (A, \Sigma)$. We show by induction on $t$ that for all $t \in T_S(X)$ and $a \in A$, $T(A_a)$ if and only if $t \in \delta^{-1}(T(A^u_a))$. The case $t \in X$ is obvious, so let $t = f(t_1, \ldots, t_m)$. If $f_a(a) = (a_1, \ldots, a_m)$, then

$$t \in T(A_a) \quad \text{iff} \quad t_1 \in T(A_{a_1}), \ldots, t_m \in T(A_{a_m})$$

$$\quad \text{iff} \quad \delta(t_1) \subseteq T(A^u_{a_1}), \ldots, \delta(t_m) \subseteq T(A^u_{a_m})$$

$$\quad \text{iff} \quad f_1 \delta(t_1), \ldots, f_m \delta(t_m) \subseteq T(A^u)$$

$$\quad \text{iff} \quad \delta(t) \subseteq T(A^u)$$

$$\quad \text{iff} \quad t \in \delta^{-1}(T(A^u)).$$

Hence, $T(A_a) = \delta^{-1}(T(A^u_a))$ and, in particular, $T(A) = \delta^{-1}(T(A^u))$. □

**Corollary 4.1.** $T(C^d) = \delta^{-1}(T(C))$ for any DR $\hat{\Sigma} X$-recognizer $C$.

**Proof.** $T(C^d) = \delta^{-1}(T(C^{du})) = \delta^{-1}(T(C))$ by Proposition 4.1 and $C^{du} = C$. □

**Proposition 4.2.** $T(A^u) = \delta(T(A))$ for any normalized DR $\Sigma X$-recognizer $A$.

**Proof.** Let $A = (A, a_0, \alpha)$ with $A = (A, \Sigma)$. The inclusion $\delta(T(A)) \subseteq T(A^u)$ follows from Proposition 4.1 and the fact that $\delta(\delta^{-1}(U)) \subseteq U$ for any $U \subseteq T_S(X)$.

For the converse inclusion we need the assumption that $A$ is normalized. It is enough to show that for all $a \in A$ and $r \in T_S(X)$, if $r \in T(A^u_a)$, then $r \in \delta(t)$ for some $t \in T(A_a)$. This we do by induction on $r$. For $r \in X$, we may let $t := r$. Next, let $r = f_s$ for some $f \in \Sigma_m$, $m \in R$, $i \in [m]$ and $s \in T(\Sigma)$, and assume that the claim holds for $s$. If $f_s(a) = (a_1, \ldots, a_m)$, then $s \in T(A^u_a)$ implies that $s \in \delta(t_i)$ for some $t_i \in T(A_{a_i})$. Since $a_i$ is not a 0-state, there is for every $j \in [m], j \neq i$ a tree $t_j \in T(A_{a_j})$. Clearly, $t := f(t_1, \ldots, t_m) \in T(A_a)$ and $r \in \delta(t)$. □

The following fact appears, in a different form, already in [16].

**Corollary 4.2.** If $T \in DRREC(\Sigma, X)$, then $\delta(T) \in DRREC(\hat{\Sigma}, X)$.

**Proposition 4.3.** A normalized DR $\Sigma X$-recognizer $A$ is minimal if and only if $A^u$ is a minimal DR $\hat{\Sigma} X$-recognizer of $\delta(T(A))$.

**Proof.** Let $A = (A, a_0, \alpha)$ with $A = (A, \Sigma)$. Consider any two states $a, b \in A$. If $T(A_a) = T(A_b)$, then $T(A^u_a) = \delta(T(A_a)) = \delta(T(A_b)) = T(A^u_b)$ by Proposition 4.2. On the other hand, if $T(A^u_a) = T(A^u_b)$, then Proposition 4.2 yields $\delta(T(A_a)) = \delta(T(A_b)) = T(A^u_a)$.
recognizing identical. Hence, $A$ is reduced if and only if $A^u$ is reduced.

It is obvious that the reachability relations $\Rightarrow^*_A$ and $\Rightarrow^*_A$ of $A$ and $A^u$ are identical. Hence, $A$ is connected if and only if $A^u$ is connected. \qed

Next we show how a DR $\Sigma$-algebra recognizing a $\Sigma$-tree language $T$ yields a DR $\hat{\Sigma}$-algebra recognizing the $\hat{\Sigma}$-languages $T_x$ ($x \in X$), and how a DR $\Sigma$-algebra recognizing $T$ is obtained from DR $\hat{\Sigma}$-algebras recognizing the $\hat{\Sigma}$-languages $T_x$.

Proposition 4.4. Let $T$ be a DR-recognizable $\Sigma$-tree language.

(a) If a finite DR $\Sigma$-algebra $A = (A, \Sigma)$ recognizes $T$, then $A^u = (A, \hat{\Sigma})$ recognizes every language $T_x$ ($x \in X$).

(b) For each $x \in X$, let $A_x = (A_x, \hat{\Sigma})$ be a finite $\hat{\Sigma}$-algebra that recognizes $T_x$. Then the direct product $\prod_x (A_x^u | x \in X)$ recognizes $T$.

Proof. Let $A = (A, a_0, \alpha)$ be a DR $\Sigma$-recognizer of $T$. It is easy to see that, for each $x \in X$, the $\hat{\Sigma}$-recognizer $A_x = (A^u, a_0, \alpha(x))$ recognizes $T_x$.

To prove (b), consider for each $x \in X$ a $\hat{\Sigma}$-recognizer $A_x = (A_x, a_{x0}, F_x)$ of $T_x$. The direct product $A := \prod_{x \in X} A_x^u$ simulates the computation of $A_x$ by its $x$-component along every path of a given tree $t \in T_\Sigma(X)$. Hence, started in state $(a_{x0})_{x \in X}$, $A$ should accept $t$ if and only if it reaches, for each $y \in X$, every $y$-labeled leaf in a state $(a_x)_{x \in X}$ such that $a_y \in F_y$. This means that $T = T(A)$ for $A = (A, (a_{x0})_{x \in X}, \alpha)$ if we define $\alpha$ by $\alpha(y) = \prod_{x \in X} G_y(x)$, where $G_y(y) = F_y$ and $G_y(x) = A_x$ for all $x \in X, x \neq y$. \qed

5 Definability by syntactic monoids

Let us first recall (cf. [2, 17]) that the syntactic congruence of a string language $L \subseteq Z^*$ is the relation $\theta_L$ on $Z^*$ defined by

$$u \theta_L v \iff (\forall w, w' \in Z^*)(wuw' \in L \iff ww' \in L),$$

and that the syntactic monoid of $L$ is the quotient monoid $M(L) := Z^*/\theta_L$.

Next we define the syntactic monoids and syntactic path monoids of tree languages introduced in [19] and [12], respectively.

Let $\xi$ be a symbol that does not appear in our alphabets $\Sigma$ or $X$. A $\Sigma X$-context is a $\Sigma(X \cup \{\xi\})$-tree in which $\xi$ occurs exactly once. The set of all $\Sigma X$-contexts is denoted by $C_{\Sigma}(X)$. If $p, q \in C_{\Sigma}(X)$ and $t \in T_{\Sigma}(X)$, then $p \cdot q = q(p)$ and $t \cdot q = q(t)$ are the $\Sigma X$-context and the $\Sigma X$-tree obtained by replacing the $\xi$ in $q$ by $p$ or $t$, respectively. Then $C_{\Sigma}(X)$ forms for the product $p \cdot q$ a monoid in which $\xi$ is the identity element. If $\Sigma$ is unary, no $X$-symbols appear in $\Sigma X$-contexts, and hence we write $C_{\Sigma}$ for $C_{\Sigma}(X)$.

The syntactic monoid congruence $\mu_T$ of a $\Sigma X$-tree language $T$ is the relation on $C_{\Sigma}(X)$ is defined by

$$p \mu_T q \iff (\forall t \in T_{\Sigma}(X))(\forall r \in C_{\Sigma}(X))(t \cdot p \cdot r \in T \iff t \cdot q \cdot r \in T),$$
and the syntactic monoid of $T$ is the quotient monoid $SM(T) := C_\Sigma(X)/\mu_T$. The syntactic path congruence $\hat{\mu}_T$ is the relation on $C_\Sigma$ defined by

$$p \hat{\mu}_T q \iff (\forall s \in T_\Sigma(X)) (r \in C_\Sigma)(s \cdot p \cdot r \in \delta(T) \iff s \cdot q \cdot r \in \delta(T)),$$

and the syntactic path monoid of $T$ is the quotient monoid $PM(T) := C_\Sigma/\hat{\mu}_T$.

In [19] it was shown that $T$ is regular if and only if $SM(T)$ is finite, and in [12] that a path closed $T$ is DR-recognizable if and only if $PM(T)$ is finite.

In [12] $PM(T)$ was defined as the quotient $\hat{\Sigma}^*/\theta_T$ where $\theta_T$ is the intersection of the congruences $\theta_{T_x}$ ($x \in X$). It is easy to see that $C_\Sigma/\hat{\mu}_T \cong \hat{\Sigma}^*/\theta_T$, and hence the next lemma follows from the fact that $\theta_T = \bigcap \{\theta_{T_x} \mid x \in X\}$. To see this, combine Theorem II.6.2 and Lemma II.8.2 of [1]. In [5] the corresponding fact about transition monoids was used.

**Lemma 5.1.** For any $T \in DRec(\Sigma, X)$, $PM(T)$ is a subdirect product of the monoids $M(T_x) \ (x \in X)$.

If $\Sigma$ is unary and we use $\Sigma$ itself as the path alphabet, then $T_\Sigma(X) = T_\Sigma(X)$ and $C_\Sigma = C_\Sigma$. Moreover, $\delta(U) = U$ for any $U \subseteq T_\Sigma(X)$, and $\hat{\mu} \Sigma$ and $\mu \Sigma$ become identical. Hence, $PM(U) \cong SM(U)$ for any unary tree language $U$. Similarly, for any ranked alphabet $\Sigma$, we may use $\Sigma$ as its own path alphabet, and then $\delta(\delta(T)) = \delta(T)$ for any $T \subseteq T_\Sigma(X)$, which implies $\hat{\mu}_T = \hat{\mu}_{\delta(T)}$. By combining these observations, we obtain the following result.

**Proposition 5.1.** $PM(T) \cong PM(\delta(T)) \cong SM(\delta(T))$ for any $\Sigma X$-tree language $T$.

In [5] Gécseg poses the following question. Assume that some property $P$ of regular string languages is determined by a class $M$ of finite monoids in the sense that a language has property $P$ if and only if its syntactic monoid is in $M$. Under what conditions can we conclude that the ‘corresponding’ property of regular tree languages is similarly determined by $M$? In [6] the question is also considered for DR tree languages in terms of syntactic path monoids. Let us describe the result of [6] concerning the DR-case.

A class $M$ of finite monoids is said to be closed under subdirect products if any subdirect product of a finite family of members of $M$ also belongs to $M$, and it is closed under subdirect factors if whenever a subdirect product of a finite family of monoids belongs to $M$, then all the factors are in $M$, too. A property $P$ of DR tree languages is path-defined by $M$ if a DR-recognizable tree language $T$ has property $P$ if and only if $PM(T) \in M$. Somewhat reformulated, Theorem 11 of [6] reads as follows.

**Proposition 5.2.** (F. Gécseg 2011) Let $P$ be a property of tree languages that is also defined for string languages, and let $M$ be a class of finite monoids. Assume that the following three conditions are satisfied.

1. A DR-recognizable $\Sigma X$-tree language $T$ has property $P$ if and only if $T_x$ has property $P$ for every $x \in X$.

4In [5, 6] this is required of subdirect products of two factors only, but the stronger form is actually used.
For string languages the property \( P \) is defined by \( M \).

(3) \( M \) is closed under subdirect products and subdirect factors. Then \( P \) is path-defined for DR-recognizable tree languages by \( M \).

Condition (3) is explained by Lemma 5.1. If \( M \) is a variety of finite monoids (VFM), i.e., if \( S(M), H(M), P_f(M) \subseteq M \), condition (3) is always satisfied. Hence, it is redundant when we consider properties that define varieties of string languages (cf. [2, 17]), and this concerns many of the best-known families of regular languages.

In what follows, we replace “properties” by families of tree or string languages.

A family of tree languages (FTL) \( V \) assigns to all pairs \( \Sigma, X \) a set \( V(\Sigma, X) \) of \( \Sigma X \)-tree languages. We write \( V = \{ V(\Sigma, X) \} \) with the understanding that \( \Sigma \) and \( X \) range over the appropriate alphabets. If \( \Sigma \) is allowed to range over the unary ranked alphabets only, then \( V \) is a family of unary tree languages (FUTL).

From any FTL \( V = \{ V(\Sigma, X) \} \) we get a FUTL \( V_u = \{ V_u(\Sigma, X) \} \) by restricting the range of \( \Sigma \) to unary alphabets. We call \( V = \{ V(\Sigma, X) \} \) a DR family of tree languages (DR-FTL) if \( V(\Sigma, X) \subseteq DRec(\Sigma, X) \) for all \( \Sigma \) and \( X \).

Let \( M \) be a class of finite monoids. For any \( \Sigma \) and \( X \), let \( M_p(\Sigma, X) := \{ T \in DRec(\Sigma, X) \mid PM(T) \in M \} \).

Then \( M_p = \{ M_p(\Sigma, X) \} \) is the DR-FTL path-defined by \( M \), and \( M^u := (M_p)^u \) is the DR-FUTL path-defined by \( M \).

Note that owing to Proposition 5.1, the third condition could be dropped in the following variant of Proposition 5.2.

**Proposition 5.3.** Let \( V = \{ V(\Sigma, X) \} \) be a DR-FTL, and let \( M \) be a class of finite monoids. If

1. \( V^u = M_p \), and
2. \( T \in V(\Sigma, X) \) if and only if \( \delta(T) \in V^u(\hat{\Sigma}, X) \) for all \( \Sigma, X \) and \( T \subseteq T_\Sigma(X) \),

then \( V = M_p \).

**Proof.** Consider any \( \Sigma \) and \( X \). For every \( T \in DRec(\Sigma, X) \),

\[
T \in M_p(\Sigma, X) \iff PM(T) \in M \iff PM(\delta(T)) \in M \\
\quad \iff \delta(T) \in M^u(\hat{\Sigma}, X) \iff \delta(T) \in V^u(\hat{\Sigma}, X) \\
\quad \iff T \in V(\Sigma, X),
\]

where we used the definition of \( M_p \), Proposition 5.1, the definition of \( M^u \), assumption (1), and finally assumption (2). Hence \( V = M_p \).

Let us now show a way to get all DR-FTLs path-defined by a VFM. For this, recall that Eilenberg [2] defines a \( * \)-variety as a family of languages with certain closure properties and shows that every \( * \)-variety \( \mathcal{L} = \{ L(Z) \} \) is defined by a unique
VFM $\textbf{M}$ in the sense that for any $L \subseteq Z^*$, $L \in \mathcal{L}(Z)$ if and only if $\text{M}(L) \in \text{M}$. For any $\ast$-variety $\mathcal{L}$, let $\mathcal{V}_\mathcal{L} = \{ \mathcal{V}_\mathcal{L}(\Sigma, X) \}$ be the FTL where

$$\mathcal{V}_\mathcal{L}(\Sigma, X) = \{ T \in D\mathcal{R}(\Sigma, X) \mid \forall x \in X \ T_x \in L(\hat{\Sigma}) \},$$

for all $\Sigma$ and $X$.

\textbf{Proposition 5.4.} If $\mathcal{L} = \{ \mathcal{L}(Z) \}$ is a $\ast$-variety and $\textbf{M}$ is the corresponding VFM, then $\mathcal{V}_\mathcal{L} = \{ \mathcal{V}_\mathcal{L}(\Sigma, X) \}$ is a DR-FTL path-defined by $\textbf{M}$.

\textit{Proof.} Let $T \in D\mathcal{R}(\Sigma, X)$. Since $\text{PM}(T)$ is a subdirect product of the monoids $\text{M}(T_x) \ (x \in X)$ and $\textbf{M}$ is a VFM, we conclude that $\text{PM}(T) \in \textbf{M}$ if and only if $\text{M}(T_x) \in \textbf{M}$ for every $x \in X$. Because $T \in \mathcal{V}_\mathcal{L}(\Sigma, X)$ if and only if $T_x \in L(\hat{\Sigma})$ for every $x \in X$, and $T_x \in L(\hat{\Sigma})$ if and only if $\text{M}(T_x) \in \textbf{M} \ (x \in X)$, this implies that $T \in \mathcal{V}_\mathcal{L}(\Sigma, X)$ if and only if $\text{PM}(T) \in \textbf{M}$. Hence, $\mathcal{V}_\mathcal{L} = \textbf{M}^\ast$.

Next we show that every DR-FTL path-defined by a VFM is obtained this way.

\textbf{Proposition 5.5.} If a DR-FTL $\mathcal{V} = \{ \mathcal{V}(\Sigma, X) \}$ is path-defined by a VFM $\textbf{M}$ and $\mathcal{L} = \{ \mathcal{L}(Z) \}$ is the $\ast$-variety defined by $\textbf{M}$, then $\mathcal{V} = \mathcal{V}_\mathcal{L}$.

\textit{Proof.} Consider any $\Sigma$ and $X$. For every $T \in D\mathcal{R}(\Sigma, X)$,

$$T \in \mathcal{V}(\Sigma, X) \text{ iff } \text{PM}(T) \in \textbf{M} \text{ iff } \text{PM}(T_x) \in \textbf{M} \text{ for every } x \in X$$

$$\text{iff } T_x \in L(\hat{\Sigma}) \text{ for every } x \in X \text{ iff } T \in \mathcal{V}_\mathcal{L}(\Sigma, X),$$

where we used the assumptions of the proposition and Lemma 5.1.

Many families of regular languages are characterized by syntactic semigroups rather than by syntactic monoids, and in [6] Gécseg gives the corresponding versions of his results. Let us modify our Propositions 5.3, 5.4 and 5.5 in the same manner.

Firstly, all languages to be considered are $\varepsilon$-free, and $\ast$-varieties are replaced by $+\ast$-varieties and VFMs by varieties of finite semigroups (VFSs). Also, instead of the syntactic monoid $\text{M}(L)$ of a language $L \subseteq Z^* := Z^* \cup \{ \varepsilon \})$ we use its syntactic semigroup $S(T)$. For these notions, cf. [2] or [17]. Furthermore, the syntactic path monoid $\text{PM}(T)$ of a $\Sigma X$-tree language is replaced by the syntactic path semigroup $S\mathcal{P}(T) := C_{\Sigma}^\ast / \tilde{\sigma}_T$, where $C_{\Sigma}^\ast := C_{\Sigma} \setminus \{ \xi \}$ and $\tilde{\sigma}_T$ is $\tilde{\sigma}_T$ restricted to $C_{\Sigma}^\ast$.

Let $T^\varepsilon(X) := T_\varepsilon(X) \setminus X$, and let us call a $\Sigma X$-tree language $T$ $\varepsilon$-free if $T \subseteq T^\varepsilon(X)$. Obviously $T$ is $\varepsilon$-free if and only if every $T_x \ (x \in X)$ is $\varepsilon$-free. Furthermore, we call a DR-FTL or a DR-FUTL $\mathcal{V} = \{ \mathcal{V}(\Sigma, X) \}$ $\varepsilon$-free if every tree language in $\mathcal{V}$ is $\varepsilon$-free. The $\varepsilon$-free DR-FTL $S^\varepsilon = \{ S^\varepsilon(\Sigma, X) \}$ path-defined by a class of finite semigroups $\textbf{S}$ is defined by

$$S^\varepsilon(\Sigma, X) := \{ T \in D\mathcal{R}(\Sigma, X) \mid T \subseteq T^\varepsilon(X), \ P\mathcal{S}(T) \in \textbf{S} \},$$

and the $\varepsilon$-free DR-FUTL path-defined by $\textbf{S}$ is $\textbf{S}^\varepsilon := \{ S^\varepsilon \}^\ast$. Finally, for any $+\ast$-variety $\mathcal{L} = \{ \mathcal{L}(Z) \}$, let $\mathcal{V}_\mathcal{L} = \{ \mathcal{V}_\mathcal{L}(\Sigma, X) \}$ be the $\varepsilon$-free DR-FTL defined by $\mathcal{V}_\mathcal{L}(\Sigma, X) := \{ T \in D\mathcal{R}(\Sigma, X) \mid T \subseteq T^\varepsilon(X), \ (\forall x \in X) \ T_x \in L(\hat{\Sigma}) \}$.

We may now state the following variants of Propositions 5.3, 5.4 and 5.5.
Proposition 5.6. Let $V = \{V(\Sigma, X)\}$ be an $\varepsilon$-free DR-FTL, and let $S$ be a class of finite semigroups. If (1) $V^n = S^n$, and (2) $T \in V(\Sigma, X)$ if and only if $\delta(T) \in V(\Sigma, X)$ for all $\Sigma, X$ and $T \subseteq T^1_\Sigma(X)$, then $V = S^\#$.

Proposition 5.7. If $L = \{L(Z)\}$ is a $+$-variety and $S$ is the corresponding VFS, then $V_L = \{V_L(\Sigma, X)\}$ is an $\varepsilon$-free DR-FTL path-defined by $S$.

Proposition 5.8. If an $\varepsilon$-free DR-FTL $V = \{V(\Sigma, X)\}$ is path-defined by a VFS $S$ and $L = \{L(Z)\}$ is the $+$-variety defined by $S$, then $V = V_L$.

6 Some examples

Let us now apply the above results to the families of DR-recognizable tree languages considered by Gécseg and Imreh [5, 6, 7, 8]. In [7] they studied monotone string and tree automata and languages. Since monotonicity is basically a property of the underlying algebras, we begin by defining monotone algebras. A $\Sigma$-algebra $A = (A, \Sigma)$ is monotone if there is a partial order $\leq$ on $A$ such that $a \leq az^k$ for all $a \in A$ and $z \in \Sigma$. A language is monotone if it is recognized by a finite monotone algebra. Let $Mon = \{Mon(Z)\}$ be the family monotone languages.

A DR $\Sigma$-algebra $A$ is monotone if $A^+$ is monotone. A $\Sigma X$-tree language is DR monotone if it is recognized by a finite monotone DR $\Sigma$-algebra. Let $DMon = \{DMon(\Sigma, X)\}$ be the DR-FTL of DR monotone tree languages. These definitions are equivalent to the ones of Gécseg and Imreh [7] and the next lemma is an immediate consequence of their corresponding results.

Lemma 6.1. A DR $\Sigma$-algebra $A = (A, \Sigma)$ is monotone if and only if the reachability relation $\Rightarrow_A$ is a partial order on $A$. Moreover, if $A$ is monotone for some partial order $\leq$, then $\Rightarrow_A b$ implies $a \leq b$ (a, b $\in A$).

Let $M_{cld}$ be the class of finite monoids in which all right-unit submonoids are closed under divisors. These notions, introduced in [7], can be defined by saying that a finite monoid $M$ belongs to $M_{cld}$ if $s(r_1 r_2) = s$ implies $s r_1 = s$ for all $s, r_1, r_2 \in M$; each $s \in M$ has its right-unit submonoid $RU(s) := \{r \in M \mid sr = s\}$. In [7] it was shown that that a regular string language is monotone if and only if its syntactic monoid is in $M_{cld}$, and in [5] Proposition 5.2 was used for showing that the DR monotone tree languages are path-defined by $M_{cld}$. That $M_{cld}$ is closed under subdirect products and factors is also implied by the following fact.

Proposition 6.1. $M_{cld}$ is a VFM.

Proof. It is clear that $S(M_{cld}), P_f(M_{cld}) \subseteq M_{cld}$. To prove $H(M_{cld}) \subseteq M_{cld}$, let $\varphi : M \to M'$ be an epimorphism and assume that $M \in M_{cld}$. If $M' \notin M_{cld}$, there are elements $a', b', c' \in M'$ such that $a'b'c' = a'$, but $a'b' \neq a'$. Let $a, b, c \in M$ be elements for which $a \varphi = a'$, $b \varphi = b'$ and $c \varphi = c'$. Since $M$ is finite, there are numbers $k \geq 0, m \geq 1$ such that $(bc)^{k+m} = (bc)^k$. Let $d := (bc)^k$. Then $d \cdot (b \cdot (c(bc)^m)) = a(bc)^{k+m} = d$ but $d \cdot b = d$ because $(d \cdot b)c = a'b'$ while $a \varphi = a'$. This would mean that $b \notin RU(d)$ although $b \cdot (c(bc)^m) \in RU(d)$. Hence, $M' \notin M_{cld}$ must hold. □
Since Mon is defined by $M_{cl}$, it follows from Eilenberg’s Variety Theorem that $Mon = \{Mon(Z)\}$ is a $*$-variety.

**Proposition 6.2.** $DMon = V_{Mon}$.

*Proof.* Let $T \in DRec(\Sigma, X)$. If $T \in DMon(\Sigma, X)$, then $T$ is recognized by a finite monotone DR $\Sigma$-algebra $A$. By Proposition 4.4, every $T_x (x \in X)$ is recognized by the monotone $\tilde{\Sigma}$-algebra $A^u$. Hence, $T \in V_{Mon}(\Sigma, X)$.

Conversely, if $T_x \in Mon(\tilde{\Sigma})$ for every $x \in X$, then each $T_x$ is recognized by a monotone $\tilde{\Sigma}$-algebra $A_x$. By Proposition 4.4 $T$ is recognized by the direct product of the algebras $A^d_x$, and this DR algebra is monotone (cf. Proposition 7.2 below). $\Box$


**Corollary 6.1.** $DMon$ is path-defined by the VFM $M_{cl}$.

As a second example we consider nilpotent DR algebras and tree languages. Since nilpotent string languages are characterized by their syntactic semigroups, we shall use Proposition 5.7. The finite and co-finite $\varepsilon$-free languages form a $*$-variety $Nil = \{Nil(Z)\}$ which corresponds to the VFS $Nil$ of finite nilpotent semigroups: a semigroup $S$ is nilpotent if it has a zero-element 0 and there is a number $k \geq 1$ such that $s_1 \cdots s_k = 0$ for all $s_1, \ldots, s_k \in S$ (cf. [2, 17]). A $\Sigma$-algebra $A = (A, Z)$ is nilpotent if there exist an element $\tilde{a} \in A$ and a number $k \geq 0$ such that $av^A = \tilde{a}$ for all $a \in A$ and every $v \in Z^*$ of length $k$. It is easy to see that the $\varepsilon$-free languages recognized by these algebras are exactly the members of $Nil$ (cf. [9], p. 125).

Let us call a DR $\Sigma$-algebra $A$ nilpotent if the $\tilde{\Sigma}$-algebra $A^u$ is nilpotent. It is clear that this definition is equivalent to the one of [8]. A $\Sigma X$-tree-language is DR nilpotent if it is recognized by a finite nilpotent DR $\Sigma$-algebra. Let $DNil = \{DNil(\Sigma, X)\}$ be the FTL of $\varepsilon$-free DR nilpotent tree languages.

**Proposition 6.3.** $DNil = V_{Nil}$.

*Proof.* The proposition follows from Proposition 4.4 and the facts mentioned above. Firstly, if $T \subseteq T^d_2 (X)$ is recognized by a finite nilpotent DR $\Sigma$-algebra $A$, then every $T_x$ is recognized by the finite nilpotent $\tilde{\Sigma}$-algebra $A^u$, and therefore belongs to $Nil(\tilde{\Sigma})$. On the other hand, if each $T_x$ is recognized by a finite nilpotent $\tilde{\Sigma}$-algebra $A_x$, then $T$ is recognized by the finite nilpotent DR $\Sigma$-algebra $\prod (A^d_x \mid x \in X)$. $\Box$

Proposition 5.7 yields the following result proved in [8].

**Corollary 6.2.** $DNil$ is path-defined by the VFS $Nil$.

As our third example we discuss the DR definite tree languages considered in [6, 8]. Let us first recall that a $Z$-algebra $A = (A, Z)$ is definite if there is a $k \geq 0$ such that $av^A = bv^A$ for all $a, b \in A$ and every $v \in Z^*$ of length $k$. The languages recognized by definite algebras are also called definite, and they are the languages of the form $E \cup Z^* F$ where, for some $k \geq 0$, $E$ is a set of words of length $< k$ and $F$ is a set of words of length $k$ (cf. [9], for example). The $\varepsilon$-free definite languages form
a \(a\)-variety \(\text{Def} = \{\text{Def}(Z)\}\) characterized by the VFS \(D\) of all finite semigroups \(S\) such that \(Se = \{e\}\) for every idempotent \(e \in S\) (cf. [2]).

Let us call a DR \(\Sigma\)-algebra \(A\) definite if the \(\hat{\Sigma}\)-algebra \(A^u\) is definite, and say that a \(\Sigma X\)-tree language is DR definite if it is recognized by a finite definite DR \(\Sigma\)-algebra. Again, these definitions are equivalent to those of [8]. Let \(D\text{Def} = \{D\text{Def}(\Sigma, X)\}\) be the DR-FTL of all \(\varepsilon\)-free DR definite tree languages.

It follows directly from our definitions and Proposition 4.4 that \(D\text{Def} = V\text{Def}\).

Hence, Proposition 5.7 yields the following result proved in [8].

**Proposition 6.4.** \(D\text{Def}\) is path-defined by the VFS \(D\).

Thus all three families of DR-recognizable tree languages shown in [6, 8] to be path-definable by a class of finite monoids or semigroups are obtained from a \(\ast\)- or a \(+\)-variety using Proposition 5.4 or Proposition 5.7. By Propositions 5.5 and 5.8 this can be expected once we know that the corresponding family of string languages is a \(\ast\)- or a \(+\)-variety. Indeed, any \(\ast\)- and \(+\)-variety will yield a DR-FTL or an \(\varepsilon\)-free DR-FTL path-definable by a VFM or a VFS, respectively.

## 7 Varieties of finite DR algebras

In this section we discuss varieties of finite DR \(\Sigma\)-algebras for an arbitrarily fixed ranked alphabet \(\Sigma\). The class operators \(S\), \(H\), \(P_f\) and \(V_f\) are defined for DR \(\Sigma\)-algebras in the natural way, and we call a class \(K\) of finite DR \(\Sigma\)-algebras a **variety of finite DR \(\Sigma\)-algebras** (DR \(\Sigma\)-VFA) if \(S(K), H(K), P_f(K) \subseteq K\).

In [3] \(\acute{E}\)sik defines \(K^u := \{A^u \mid A \in K\}\) for any class \(K\) of DR \(\Sigma\)-algebras. He noted that \(K\) is a variety of DR \(\Sigma\)-algebras if and only if \(K^u\) is a variety of \(\hat{\Sigma}\)-algebras, and that notions from the theory of varieties of algebras may therefore be extended to DR algebras. We shall apply the operation \(K \mapsto K^u\) to classes of finite DR \(\Sigma\)-algebras, and we also introduce the converse operation that associates with each class \(U\) of finite \(\hat{\Sigma}\)-algebras the class \(U^d := \{C^d \mid C \in U\}\) of finite DR \(\Sigma\)-algebras. Obviously, \(K^{ud} = K\) and \(U^{du} = U\).

**Lemma 7.1.** Let \(K\) be a class of finite DR \(\Sigma\)-algebras and \(U\) be a class of finite \(\hat{\Sigma}\)-algebras. Then

(a) \(H(K)^u = H(K^u)\), \(S(K)^u = S(K^u)\) and \(P_f(K)^u = P_f(K^u)\), and

(b) \(H(U)^d = H(U^d)\), \(S(U)^d = S(U^d)\) and \(P_f(U)^d = P_f(U^d)\).

Hence, \(K\) is a DR \(\Sigma\)-VFA if and only if \(K^u\) is a \(\hat{\Sigma}\)-VFA, and \(U\) is a \(\hat{\Sigma}\)-VFA if and only if \(U^d\) is a DR \(\Sigma\)-VFA.

**Proof.** The equalities in (a) and (b) are immediate consequences of Lemma 3.1, and the remaining claims follow from them.

An easy modification of Tarski’s well-known HSP-theorem (cf. [1], p. 61) yields \(V_f(K) = HSP_f(K)\) for any ranked alphabet \(\Sigma\) and any class \(K\) of finite \(\Sigma\)-algebras (cf. [18], for example). Let us derive the corresponding representation for finite DR \(\Sigma\)-algebras.
Proposition 7.1. \( V_f(K) = HSP_f(K) \) for any class \( K \) of finite DR \( \Sigma \)-algebras.

Proof. Clearly, \( K \subseteq HSP_f(K) \). As a special case of the fact noted above, we get \( V_f(K^u) = HSP_f(K^u) \). This means, in particular, that \( HSP_f(K^u) \) is a \( \tilde{\Sigma} \)-VFA. Since \( HSP_f(K)^u = HSP_f(K^u) \), this implies by Lemma 7.1 that \( HSP_f(K) \) is a DR \( \Sigma \)-VFA. If \( L \) is a DR \( \Sigma \)-VFA with \( K \subseteq L \), then \( HSP_f(K) \subseteq HSP_f(L) = L \). Hence, \( HSP_f(K) \) is the DR \( \Sigma \)-VFA generated by \( K \).

Lemma 7.1 and Proposition 7.1 yield the following fact.

Corollary 7.1. \( V_f(K) = V_f(K^u)^d \) for any class \( K \) of finite DR \( \Sigma \)-algebras.

Let \( DMon_\Sigma \), \( DNil_\Sigma \) and \( DDef_\Sigma \) denote the classes of all finite monotone, nilpotent and definite DR \( \Sigma \)-algebras, respectively.

Proposition 7.2. \( DMon_\Sigma \), \( DNil_\Sigma \) and \( DDef_\Sigma \) are DR \( \Sigma \)-VFAs.

Proof. By Lemma 7.1, it suffices to verify that the corresponding classes \( DMon_\Sigma^u \), \( DNil_\Sigma^u \) and \( DDef_\Sigma^u \) of unary algebras are \( \Sigma \)-VFAs.

Gécseg and Imreh [7] proved that all finite direct products and homomorphic images of monotone finite automata are monotone. These results apply directly to unary algebras, and hence \( P_f(DMon_\Sigma^u) \subseteq DMon_\Sigma^u \) and \( H(DMon_\Sigma^u) \subseteq DMon_\Sigma^u \). Since it is clear that subalgebras of monotone algebras are monotone, we may conclude that \( DMon_\Sigma^u \) is a \( \tilde{\Sigma} \)-VFA.

In [18] it was noted that for any ranked alphabet \( \Sigma \), the finite nilpotent \( \Sigma \)-algebras form an \( \Sigma \)-VFA, and in [4] Œsek proved the corresponding fact about finite definite \( \Sigma \)-algebras. Hence, also \( DNil_\Sigma^u \) and \( DDef_\Sigma^u \) are \( \tilde{\Sigma} \)-VFAs.

Let us now consider equational definitions of DR \( \Sigma \)-VFAs. The terms appearing in \( \Sigma \)-identities are written as expressions \( \xi u \), where \( \xi \) is a variable and \( u \in \tilde{\Sigma}^* \). There are two types of \( \tilde{\Sigma} \)-identities, the regular identities \( \xi u \approx \xi v \) and the irregular identities \( \xi u \approx \xi' v \), in which \( \xi \) and \( \xi' \) are two distinct variables. A \( \tilde{\Sigma} \)-algebra \( C = (C, \tilde{\Sigma}) \) satisfies \( \xi u \approx \xi' v \) if \( u^c = v^{c'} \), and it satisfies \( \xi u \approx \xi' v \), where \( \xi \neq \xi' \), if \( cu^b = dv^{c'} \) for all \( c, d \in C \). Furthermore, \( C \) ultimately satisfies an \( \omega \)-sequence

\[
E = (\ell_0 \approx r_0, \ell_1 \approx r_1, \ell_2 \approx r_2, \ldots)
\]

of \( \Sigma \)-identities if there exists an \( n_0 \geq 0 \) such that \( C \) satisfies \( \ell_n \approx r_n \) for every \( n \geq n_0 \). The class \( E^u \) of finite \( \tilde{\Sigma} \)-algebras ultimately defined by \( E \) consists of the finite \( \tilde{\Sigma} \)-algebras ultimately satisfying \( E \). By a well-known theorem by Eilenberg and Schützenberger (cf. [2, 17]), a class \( K \) of finite \( \tilde{\Sigma} \)-algebras is a \( \tilde{\Sigma} \)-VFA if and only if \( K = E^u \) for some \( \omega \)-sequence \( E \) of \( \tilde{\Sigma} \)-identities.

Following Œsek [3] we say that a DR \( \Sigma \)-algebra \( A \) satisfies a \( \tilde{\Sigma} \)-identity \( \ell \approx r \) if \( A^u \) satisfies \( \ell \approx r \). Naturally, \( A \) ultimately satisfies an \( \omega \)-sequence \( E \) of \( \tilde{\Sigma} \)-identities if \( A^u \) ultimately satisfies \( E \). The class of finite DR \( \Sigma \)-algebras ultimately satisfying \( E \) is denoted by \( E^u \). Thus \( E^u \) is a class of \( \tilde{\Sigma} \)-algebras and \( E^{ud} := (E^u)^d \) is the corresponding class of DR \( \Sigma \)-algebras. Similarly, \( E^{du} := (E^d)^u \) is the class of \( \tilde{\Sigma} \)-algebras corresponding to the class \( E^d \) of DR \( \Sigma \)-algebras. Since \( E^{ud} = E^d \) and
$E^{du} = E^u$, the next proposition follows from the Eilenberg-Schützenberger theorem and Lemma 7.1.

**Proposition 7.3.** A class $K$ of finite DR $\Sigma$-algebras is a DR $\Sigma$-VFA if and only if $K = E^d$ for some $\omega$-sequence $E$ of $\Sigma$-identities.

### 8 Concluding remarks

We have considered some aspects of DR tree recognizers and DR-recognizable tree languages. Our algebraic approach is in a large part based on the connection between DR algebras and unary algebras put forward by Ésik [3]. It was used for describing the relationship between a DR-recognizable tree language and its path language as well as in the discussion of varieties of finite DR algebras.

In Section 5 we showed that any $*$- or $+$-variety defines a family of DR-recognizable tree languages path-definable by a variety of finite monoids or a variety of finite semigroups, respectively. Hence there are many families of DR-recognizable tree languages that could be investigated similarly as the families $DMon$, $DNil$ and $DDef$ were studied in the papers [7, 8, 13, 14]. On a more general level, one should describe the common properties of all such families. In particular, it is conceivable that they are characterized by some closure properties. It is also natural to consider the families of DR-recognizable tree languages that correspond to a varieties of finite DR algebras. Such questions belong to a variety theory of DR-recognizable tree languages still to be developed.

### References


