

On homomorphically α_i -complete systems of automata

By P. DÖMÖSI

In [2] there is introduced a family of semi-cascade products named α_i -products, where the index i is a nonnegative integer, which denotes the maximal admissible length of feedbacks. By results of F. GÉCSEK (see for example [3]) it can be seen that there exist no finite homomorphically complete systems with respect to the α_0 - and α_1 -products.

From [1] it follows that every automaton having n states can be represented (in a certain sense) by an α_0 -product of automata, such that all components of this product are either two-state reset automata, or special n -state automata, named "standard automata". Using results of [4] we get that these "standard automata" can be embedded state-isomorphically into an α_2 -product of two-state automata. Therefore, taking into consideration the fact that an α_0 -product of α_2 -products is an α_2 -product, every automaton can be represented (in a certain sense) by an α_2 -product of two-state automata.

In this paper we present a direct proof of this statement. By this result we receive that for every $i \geq 2$ there exists a finite homomorphically complete system of automata with respect to the α_i -product. For the notions and notations that will not be defined here, we refer to the book [3].

By an *automaton* $A = (X, A, Y, \delta, \lambda)$ we mean a finite Mealy-type automaton, where X, A and Y are the finite input, state and output sets, respectively; furthermore $\delta: A \times X \rightarrow A$ denotes the transition and $\lambda: A \times X \rightarrow Y$ is the output function.

Let $A_t = (X_t, A_t, Y_t, \delta_t, \lambda_t)$ ($t=1, \dots, n$) be a system of automata. Moreover, let X and Y be finite nonvoid sets and

$$\varphi: A_1 \times \dots \times A_n \times X \rightarrow X_1 \times \dots \times X_n, \quad \psi: A_1 \times \dots \times A_n \times X \rightarrow Y$$

mappings. We say that the automaton $A = (A, X, Y, \delta, \lambda)$ with $A = A_1 \times \dots \times A_n$, $\lambda((a_1, \dots, a_n), x) = \psi(a_1, \dots, a_n, x)$

$$\delta((a_1, \dots, a_n), x) = (\delta_1(a_1, \varphi_1(a_1, \dots, a_n, x)), \dots, \delta_n(a_n, \varphi_n(a_1, \dots, a_n, x))),$$

is the α_i -product of A_t ($t=1, \dots, n$) with respect to X, Y, φ, ψ if φ can be given in the form $\varphi(a_1, \dots, a_n, x) = (\varphi_1(a_1, \dots, a_n, x), \dots, \varphi_n(a_1, \dots, a_n, x))$, such that φ_j ($1 \leq j \leq n$) is independent of states having indices greater than or equal to $j+i$, where i is a fixed nonnegative integer. For this product we shall use the short notation

$A = \prod_{i=1}^n A_i [X, Y, \varphi, \psi]$. The mappings φ and ψ are called *feedback function* and *output function*, respectively.

Let A, B be a pair of automata. We say that A can be embedded state-isomorphically into B if B has an A -subautomaton B' , such that B' is A -isomorphic to A . If B has an A -subautomaton B' , such that B' can be mapped A -homomorphically onto A then it is said that A can be strongly covered (or can be represented) by B .

Take a nonnegative integer i . Any system Σ of automata is *homomorphically complete with respect to the α_i -product*, or briefly, Σ is *homomorphically α_i -complete* if every automaton can be strongly covered by an appropriate α_i -product of components from Σ . Moreover, the system Σ is *finite* if it has finite-many elements.

Consider an automaton $A = (X, A, Y, \delta, \lambda)$ with n states. For an arbitrary positive integer $m \leq n$ we say that A is *m -husked* if there exists an arrangement a_1, \dots, a_n of states in A , such that for $a_l \in A, x \in X, l < m$ we have $\delta(a_l, x) \in \langle a_1, \dots, a_{l+1} \rangle$. (Obviously, for $m=1$ this is a formal requirement. Therefore, all automata are 1-husked.)

If an automaton A with n states is n -husked then it is said to be *right-husked*. (We note that all $(n-1)$ -husked automata with $n > 1$ states need necessarily be right-husked.)

The following holds.

Lemma 1. Every m -husked automaton A having $n > m$ states can be strongly covered by a suitable α_0 -product $M = \prod_{i=1}^2 A_i [X, Y, \varphi, \psi]$ whose components satisfy the following conditions:

- (i) A_1 has $n-m$ states;
- (ii) A_2 is an $(m+1)$ -husked automaton the number of states of which is equal to n .

Proof. Take an m -husked automaton $A = (X, A, Y, \delta, \lambda)$ with $n > m$ number of states and let a_1, \dots, a_n be an arrangement of states in A , such that for $a_l \in A, x \in X, l < m$ it holds that $\delta(a_l, x) \in \langle a_1, \dots, a_{l+1} \rangle$. For any triplet $u, v, w \in \{1, \dots, n\}$ we introduce the notation

$$a_{(u,v,w)} = \begin{cases} a_u & \text{if } u \notin \langle v, w \rangle, \\ a_v & \text{if } u = w, \\ a_w & \text{if } u = v. \end{cases}$$

Construct the automata $A_1 = (X, B, B \times X, \delta_1, \lambda_1)$ and $A_2 = (B \times X, A, Y, \delta_2, \lambda_2)$ in the following way. $B = \langle m+1, \dots, n \rangle$, furthermore, for every triplet $v \in B, a_l \in A, x \in X$

$$\delta_1(v, x) = \begin{cases} v & \text{if } \delta(a_m, x) \in \langle a_1, \dots, a_m \rangle, \\ w & \text{if } \delta(a_m, x) \notin \langle a_1, \dots, a_m \rangle \text{ and } \delta(a_m, x) = a_w, \end{cases}$$

$$\delta_2(a_l, (v, x)) = \begin{cases} a_{(z, m+1, v)} & \text{if } \delta(a_m, x) \in \langle a_1, \dots, a_m \rangle \text{ and } \delta(a_{(l, m+1, v)}, x) = a_z, \\ a_{(z, m+1, w)} & \text{if } \delta(a_m, x) = a_w \notin \langle a_1, \dots, a_m \rangle \\ & \text{and } \delta(a_{(l, m+1, v)}, x) = a_z, \end{cases}$$

$$\lambda_1(v, x) = (v, x), \quad \lambda_2(a_l, (v, x)) = \lambda(a_{(l, m+1, v)}, x).$$

Define the α_0 -product $M = \sum_{t=1}^2 A_t [X, Y, \varphi, \psi]$, where in case of every pair $(v, a_t) \in B \times A, x \in X$

$$\varphi(v, a_t, x) = (x, (v, x)),$$

$$\psi(v, a_t, x) = \lambda_2(a_t, (v, x)).$$

By an elementary computation we obtain that the mapping $\mu: B \times A \rightarrow A$ with $\mu(v, a_t) = a_{(t, m+1, v)}$ is an A -homomorphism of M onto A . By the definitions of A_1 and A_2 this completes the proof of Lemma 1.

The following statement is trivial.

Lemma 2. Let $\langle A_1, \dots, A_n \rangle$ and $\langle B_1, \dots, B_m \rangle$ be arbitrary finite systems of automata. If any automaton A can be strongly covered by an α_0 -product of components from $\langle A_1, \dots, A_n \rangle$, moreover, an element A_t of $\langle A_1, \dots, A_n \rangle$ can be strongly covered by an α_0 -product of components from $\langle B_1, \dots, B_m \rangle$ then A can be strongly covered by an α_0 -product of components from $\langle A_1, \dots, A_{t-1}, B_1, \dots, B_m, A_{t+1}, \dots, A_n \rangle$.

Using Lemma 1 and Lemma 2 by an induction we get the following

Lemma 3. Every automaton A can be strongly covered by an α_0 -product of right-husked automata having not more states than A .

Lemma 4. Every right-husked automaton can be embedded state-isomorphically into and α_2 -product of two-state automata.

Proof. Let $A = (X, A, Y, \delta, \lambda)$ be an arbitrary right-husked automaton and take an arrangement a_1, \dots, a_n of its states with $\delta(a_t, x) \in \langle a_1, \dots, a_{t+1} \rangle$ ($t=1, \dots, n-1, x \in X$). Consider the automaton $B = (\langle u, v \rangle, \langle 0, 1 \rangle, \langle z \rangle, \delta_B, \lambda_B)$ where $\delta_B(0, u) = \delta_B(1, v) = 0, \delta_B(0, v) = \delta_B(1, u) = 1$ and $\lambda_B(j, x) = z$ for any $j \in \langle 0, 1 \rangle, x \in \langle u, v \rangle$.

Construct the α_2 -product $C = (X, C, Y, \delta_C, \lambda_C) = \prod_{t=1}^n B_t [X, Y, \varphi, \psi]$ with $B_1 = \dots = B_n = B$ as follows. For any $1 \leq s \leq n, (d_1, \dots, d_n) \in \prod_{t=1}^n B_t$ and $x \in X$

$$\varphi_s(d_1, \dots, d_n, x) = \begin{cases} v & \text{if } d_j = 1, \delta(a_{n-j+1}, x) = a_{n-s+1} \text{ for some} \\ & j \in \langle 1, \dots, s-1, s+1 \rangle \cap \langle 1, \dots, n \rangle \text{ or} \\ & d_s = 1, \delta(a_{n-s+1}, x) \neq a_{n-s+1}, \\ u & \text{otherwise,} \end{cases}$$

$$\psi(d_1, \dots, d_n, x) = \begin{cases} \lambda(a_{n-j+1}, x) & \text{if } d_j = 1 \text{ for some } 1 \leq j \leq n \\ & \text{and } \sum_{t=1}^n d_t = 1, \\ \text{arbitrary fixed element of } Y & \text{otherwise.} \end{cases}$$

Denote C' the set of all elements $(d_1, \dots, d_n) \in \prod_{t=1}^n B_t$ for which $\sum_{t=1}^n d_t = 1$. It is clear that $C' = (X, C', Y, \delta_{C|C' \times X}, \lambda_{C|C' \times X})$ is an A -subautomaton of C . Now con-

Consider the mapping $v: (d_1, \dots, d_n) \rightarrow a_{\sum_{t=1}^n d_t \cdot (n-t+1)} ((d_1, \dots, d_n) \in C')$. It can be seen that v is an A -isomorphism of C' onto A . This ends the proof of Lemma 4.

It is evident that any α_0 -product of α_2 -products also is an α_2 -product. Therefore, by Lemma 3 and Lemma 4, the following result is shown.

Theorem. Every automaton can be strongly covered by an α_2 -product of two-state automata.

We know, by definition, that for every $i > 2$ the concept of α_i -product is a generalization of α_2 -product. (In [4] it is shown that this generalization is proper.) Thus, the above Theorem and our remark about α_0 -product and α_1 -product jointly imply the following result.

Corollary. For every nonnegative integer i there exists a finite homomorphically α_i -complete system if and only if $i \geq 2$.

DEPT. OF MATHEMATICS
KARL MARX UNIVERSITY OF ECONOMICS
DIMITROV TÉR 8.
BUDAPEST, HUNGARY
H-1093

References

- [1] Евтушенко, Н. В., К реализации автоматов каскадным соединением стандартных автоматов, *Автоматика и Вычислительная Техника*, 1979, № 2, pp. 50—53.
- [2] GÉCSEG, F., Composition of automata, *Proceedings of the 2nd Colloquium on Automata, Languages and Programming*, v. 14, 1974, pp. 351—363.
- [3] GÉCSEG, F. and I. PEÁK, *Algebraic theory of automata*, Akadémiai Kiadó, Budapest, 1972.
- [4] IMREN, B., On α_i -products of automata, *Acta Cybernet.*, v. 3, 1978, pp. 301—307.

(Received Dec. 19, 1981)